Abdullah Erzin

Computer Vision Engineer

PROFILE

I am a dedicated Computer Vision Engineer with a passion for pushing the boundaries of technology, I have gained valuable experience in developing computer vision and AI solutions throughout my career. My career goal is to continue exploring and advancing the field of computer vision and AI. I strive to contribute my expertise and leadership skills to develop impactful solutions that address real-world challenges. I aim to collaborate with talented teams and utilize my programming

EXPERIENCE

Computer Vision Engineer, Dogru Holding A.S — May 2023- Present I am joined a small group to develop computer vision and ai solutions in Dogru Holding. I am leading a face recognition project for the security and a project to

control a crane the area where is not proper to human

ZGN is a also Dogru Holding's company, I change the company to focus on the Computer Vision projects.

Autonomous Vehicle Development Engineer, ZGN Autonomous & Robotics — Dec 2022 - May 2023

I worked on autonomous driving algorithms development projects.

Machine Vision Engineer, Gensys Automation & Machine Vision, Gebze, Kocaeli — Dec 2021 - Dec 2022

In my first job, I progressively assumed responsibilities in image processing projects and actively participated in field studies. Eventually, I successfully completed and presented a comprehensive NDT project, taking charge of the entire process from research and initial demo preparation to project management

Intern, Mavis Machine Vision Software, Gebze, Kocaeli — Jul 2020 - Mar 2021 I learned the fundamental of Machine Vision, industrial cameras and OOP with C#

EDUCATION

Mechatronic Engineering - Marmara University, Istanbul, Turkey — Mar 2021

SKILLS

I currently use a Python, but I had work with C# and Halcon. I could easily switch the language

I work with the group projects so i can use Git

<u>abdullaherzin80@gmail.com</u> +90 (531) 594 55 28 <u>linkedin.com/in/abdullah-erzin</u> <u>erzn3522.github.io/</u> abdullaherzin.medium.com/